

**ROTARY ELECTRIC MOTOR HAVING SEPARATE CONTROL  
MODULES FOR RESPECTIVE STATOR ELECTROMAGNETS**

**Related Applications**

This application contains subject matter related to copending U.S. Application serial number 09/826,423 of Maslov et al., filed April 5, 2001, copending U.S. Application serial number 09/826,422 of Maslov et al., filed  
5 April 5, 2001, and U.S. Application serial number 09/966,102, filed October 1, 2001. These applications are commonly assigned with the present application. The disclosures of these copending applications are incorporated by reference herein.

10 **Field of the Invention**

The present invention relates to rotary electric motors, more particularly to motors wherein the stator is formed of individual modules, each module comprising core and winding structure, electrical control and drive elements, and a power supply integrated therein.

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**Background**

The progressive improvement of electronic systems, such as microcontroller and microprocessor based applications for the control of motors, as well as the availability of improved portable power sources, has made the

development of efficient electric motor drives for vehicles, as a viable alternative to internal combustion engines, a compelling challenge. Electronically controlled pulsed energization of windings of motors offers the prospect of more flexible management of motor characteristics. By control of pulse width, duty cycle, and switched application of a battery source to appropriate stator windings, functional versatility that is virtually indistinguishable from alternating current synchronous motor operation can be achieved. The use of permanent magnets in conjunction with such windings is advantageous in limiting current consumption.

10           The above-identified copending related U.S. patent application Serial No. 09/826,422 of Maslov et al. identifies and addresses the need for an improved motor amenable to simplified manufacture and capable of efficient flexible operating characteristics. In a vehicle drive environment, it is highly desirable to attain smooth operation over a wide speed range, while maintaining a high torque output capability at minimum power consumption. Such a vehicle motor drive should advantageously provide ready accessibility to the various structural components for replacement of parts at a minimum of inconvenience. The copending related U.S. application incorporates electromagnet poles as isolated magnetically permeable structures configured in an annular ring, relatively thin in the radial direction, to provide advantageous effects. With this arrangement, flux can be concentrated, with virtually no loss or deleterious transformer interference effects in the electromagnet cores, as compared with prior art embodiments. While improvements in torque

characteristics and efficiency are attainable with the structure of the identified  
compending application, further improvements remain desirable.

To this end, the above-identified compending related U.S. patent  
application Serial No. 09/826,423 of Maslov et al. seeks to optimize rotor  
5 parameters such as the grade of the magnet, the energy density and the overall  
magnetic characteristics of the magnet grade, the size and the dimensions of  
the magnet that can adjust the permanence and the overall operating condition  
of the magnet when it is part of the rotor, the temperature stability of the  
magnet, the finishing, coating and post processing steps taken in  
10 manufacturing of the magnets for the intended application, the stability of the  
magnetization over the curvilinear surface of the magnet, uniformity of the  
radial polarization of the magnet, the adjacent gap between two separate  
magnets, the mechanical features of the edges of the magnets, and the return  
flux path of the magnet as provided by a back iron ring section.

15 In environments in which portability and size are important factors, the  
need exists for drive motors that are capable of a wide range of operating  
characteristics, without sacrificing complex control functionality. Brushless  
motor systems should have the capability to control each of a plurality of  
electronic switches to provide accurate commutation sequencing and  
20 appropriate application of power to the individual stator windings. The above-  
identified compending related U.S. patent application of Maslov et al. (Atty.  
docket 57357-016) describes a motor structural configuration in which the  
control elements, which can be complex and diverse, are contained within the  
confines of the stator. The stator flux producing structure, streamlined to a

relatively thin annular configuration to accommodate placement of the elements therein, nevertheless is capable of producing appropriate flux output while providing high torque at low operating speeds.

Various advantages attributable to the provision of multiple separate stator magnetic paths in comparison to a single common path in the stator body have been described above. Easy accessibility to the interior of the stator and the structural and electrical components therein present additional opportunities for improved operation.

#### 10 **Disclosure of the Invention**

The present invention fulfills the above described needs, while providing additional benefits of the isolated individual pole pair arrangements disclosed in the identified Maslov et al. applications. The stator is formed of a plurality of individual power modules and corresponding core segments, each module comprising electrical control and drive elements supplied by a power source incorporated within the stator. Such parallel architecture provides relatively independently controlled functionality for each module. Performance of each module individually may be measured *in situ* during normal operation or by running more extensive, software controlled, diagnostic routines. Based on test results, a module can be automatically recalibrated, disconnected, or flagged for repair or replacement. Overall motor performance, determined by combining the characteristics of the independent modules, can be compared to original benchmarks to analyze various repair options for devising the minimum necessary action.

Each module and stator core segment can be individually installed and removed without disturbing the other units. Should a particular module or stator core segment fail, it can be deactivated without significantly affecting the overall performance of the remaining stator modules. Thereafter, the faulty element can  
5 be easily removed and tested externally while permitting the motor to operate with the remaining modules. The faulty component can then be identified and repaired or replaced. At a convenient time, the repaired or replacement unit can be easily reinstalled in its stator compartment.

The thin annular ring configuration of the stator electromagnet core  
10 elements provides sufficient space to allocate a substantial portion, if not all, of a relatively complex electrical control system within the confines of the stator structure. Integration of the electrical control components within a shielded space internal to the stator flux producing structure provides several advantages. Simplification of integration is obtained while avoiding electromagnetic  
15 interference between the motor and outside environment as well as between the control circuit and the switched stator windings. When used, for example, in specific applications such as vehicle drives, the incorporation of both motor structure and the electrical control system within the vehicle wheel can provide a decrease in weight of the unit, while also decreasing acoustic and mechanical  
20 noise. Operation from the user's perspective can be simplified to simulate, for example, conventional automobile operation.

The aforementioned advantages are manifested in structural features of the invention, at least in part, wherein the motor comprises a rotor and stator each disposed in an angular ring configuration and spaced from each other by





Additional advantages of the present invention will become readily apparent to those skilled in this art from the following detailed description, wherein only the preferred embodiment of the invention is shown and described, simply by way of illustration of the best mode contemplated of carrying out the invention. As will be realized, the invention is capable of other and different embodiments, and its several details are capable of modifications in various obvious respects, all without departing from the invention. Accordingly, the drawings and description are to be regarded as illustrative in nature, and not as restrictive.

#### **Brief Description of Drawings**

The present invention is illustrated by way of example, and not by way of limitation, in the figures of the accompanying drawing and in which like reference numerals refer to similar elements and in which:

Fig. 1 is a partial three dimensional perspective view of a motor according to the present invention.

Fig. 2 is an exploded view of the structural components of the motor of Fig. 1 illustrative of the positional relationship among the various elements.

Fig. 3 is a perspective external view of the motor of Figs. 1 and 2.

Fig. 4 is a block diagram of a control system suitable for use in the motor of Figs. 1-3.

Fig. 5 is a partial block diagram for a winding switching circuit of the system of Fig. 4.



Fig. 6 is a partial three dimensional perspective view of a variation of the motor structural arrangement shown in Fig. 1, in accordance with the present invention.

Figs. 7a - 7c are illustrative of an alternative stator construction according to the present invention.

### **Detailed Description of the Invention**

The motor of the present invention is suitable for use in driving a vehicle wheel of an automobile, motorcycle, bicycle, or the like. The drawing illustrations thus depict motor structure that can be housed within a vehicle wheel, the stator rigidly mounted to a stationary shaft and surrounded by a rotor for driving the wheel. It should be appreciated, however, that the vehicle context is merely exemplary of a multitude of particular applications in which the motor of the present invention may be employed.

Fig. 1 is a cutaway drawing of the motor structure, the elements shown in more detail in the exploded view of Fig. 2. Motor 10 comprises annular permanent magnet rotor 20 and annular stator structure 30 separated by a radial air gap. The rotor and stator are configured coaxially about an axis of rotation, which is centered in stationary shaft 36. The stator comprises a plurality of ferromagnetically isolated elements, or stator groups. Core segments 32, made of magnetically permeable material separated from direct contact with each other, have respective winding portions 34 formed on each pole. Seven stator groups are shown, each group comprised of two salient electromagnet poles, allocated circumferentially along the air gap. The rotor

comprises a plurality of permanent magnets 22, circumferentially distributed about the air gap and affixed to a non-magnetic annular back plate 24, which may be formed of aluminum or other non magnetically permeable material. The back plate is part of the motor housing to which is attached side walls 26.

5           The flux distributions produced by the rotor magnets may be enhanced by the provision of a magnetically permeable element, not shown, mounted to the back of the rotor magnets. Sixteen rotor magnets are shown. It is to be understood that the numbers of stator poles and rotor magnets illustrated are merely exemplary, as various ratios can be utilized, depending on desired  
10   operational parameters. For example, fewer electromagnets spaced at greater distances may produce different speed characteristics. The stator core segments are secured to a rigid skeletal structure 40 that is centrally fixed to the shaft 36. Spine members 42, equal in number to the number of stator groups, extend radially away from the center of structure 40 to U-shaped plates  
15   44. The U-shaped plate sides and the stator core segments contain mating holes by which the stator segments can be fixed to the skeletal structure. Each U-shaped plate engages an adjacent pair of stator segments.

Each stator segment and adjoining pair of spine members together define a space within which circuit elements are contained. The rigid spine  
20   portions 42 have sufficient surface area to provide the necessary structural support as well as to accommodate circuit boards 46. A circuit board may be affixed to each spine portion in any conventional manner. Each circuit board contains the control circuit elements and switches needed for application of energizing current through appropriate wiring connections to a winding of a

stator core segment to which the spine portion is attached. It should be appreciated that all control circuit elements and switches can be integrated into a single circuit board to provide even greater economy of space and weight.

The motor power supply, represented by batteries 48, is also self-contained within the stator spaces. Appropriate receptacles (not shown) for the batteries can be fixed to the spine portions 42. The receptacles, which may be of any conventional variety, permit easy removal of the batteries for replacement or recharge. While a single battery is shown for each stator module, the illustration is representative of an energy source that may take the form of a battery pack, a plurality of batteries, or any variations of well known voltage sources. That is, any commercially available battery type or battery pack that is of sufficient capacity to supply the necessary motor power may be used. Thus, depending on particular battery characteristics and motor drive requirements, it is possible to use the module spaces for location of other elements.

Fig. 3 is a three dimensional external view of the motor system of Figs. 1 and 2. The rotor housing outer ring 24 and side walls 26 are configured to form a wheel hub on which a tire, not shown, can be mounted. The rotor wheel housing is journaled for rotation about the stationary shaft 36 via bearings 38. The cylindrical rotor housing structure surrounds the stator annular ring that is coextensively aligned in the axial direction with the rotor across the air gap.

Fig. 4 is a block diagram of a typical control system that may be employed to drive the motor structure shown in Figs. 1-3. Stator windings 34

are switchably energized by driving current supplied from power source 50 via electronic switch sets 52. Timing of the current pulses is subject to the control of sequence controller 60, which is responsive to feedback signals received from position sensor 62. Sequence controller may include a microprocessor or  
5 equivalent digital signal processor. Although position sensor 62 is schematically represented by a single unit, several sensors may be appropriately distributed at stator sections along the air gap to detect rotor magnet rotation. The position sensor may comprise any known magnetic sensing devices, such as a Hall effect devices, giant magneto resistive (GMR)  
10 sensors, reed switches, pulse wire sensors, amorphous sensors, resolvers or optical sensors.

The use of controlled electronic switches for application of energizing current to motor windings is common in the art. Fig. 5 is a partial circuit diagram of a switch set and driver for an individual stator core segment  
15 winding. Stator winding 34 is connected in a bridge circuit of four FETs. It is to be understood that any of various known electronic switching elements may be used for directing driving current in the appropriate direction to stator winding 34 such as, for example, bipolar transistors. FET 53 and FET 55 are connected in series across the power source, as are FET 54 and FET 56. Stator  
20 winding 34 is connected between the connection nodes of the two series FET circuits. Gate driver 58 is responsive to control signals received from the sequence controller 60 to apply activation signals to the gate terminals of the FETs. FETs 53 and 56 are concurrently activated for motor current flow in one direction. For current flow in the reverse direction, FETs 54 and 55 are

concurrently activated. Gate driver 58 may be integrated into sequence controller 60 or comprise a separate driver circuit.

Fig. 6 is a partial three dimensional perspective view of a variation of the motor structural arrangement shown in Fig. 1. Instead of providing a separate winding portion on each of the electromagnet stator poles, winding 34 of each stator core segment is formed on a core section that links the poles. In proximity to each of the stator cores sections is a position sensor 62, which generates output signals indicative of rotor position relative to the corresponding stator core section. The output signals are applied to control circuitry contained on circuit board 46.

Figs. 7a - 7c are illustrative of an alternative structural arrangement of the stator in accordance with the present invention. A plurality of fifteen core segments 31 are shown, each segment comprising a pair of salient poles 32 and a linking portion 33. The core segments are each constructed of magnetically permeable material. Each segment pole pair is aligned in a direction parallel to the axis of rotation and has a winding 34 formed on each pole. Linking portion 33 is a relatively thin segment joined at its outer peripheral surface to the salient poles 32 while having an inner peripheral surface that is somewhat concave. The degree of concavity is commensurate with the radial spacing of core segments from the axis of rotation so that the core segments are configured generally circumferentially. Linking portion 33 extends in the circumferential direction on either side beyond the salient poles.

The stator core segments are secured to a rigid skeletal structure 140 that is centrally fixed to the shaft 36. Skeletal structure 140 is formed of a

non-magnetically permeable material, such as plastic or aluminum. The skeletal structure, which is fixed to shaft 36, comprises spine members 142 integrally formed with a generally circumferential portion 144. As can be seen more clearly in Figs. 7b and 7c, portion 144 comprises a relatively thin cylindrical sleeve 145 having rib members 146 on its radially outer periphery. The rib members extend outwardly from the sleeve and are generally parallel to the axis of rotation. Each rib member has flanged portions 148 near its outer extent to form grooves with the sleeve 145. Adjacent ribs 146 are joined at one end of the sleeve by an additional ribbed groove portion 149.

Adjacent ribs and adjoining groove portions therebetween form outer slots that accommodate stator linking portions 33. Thus, for the fifteen stator core segments, fifteen slots are provided by the skeletal structure. As can be seen in Fig. 7b, a stator segment may be easily inserted into the skeletal support structure by sliding the core segment linking portion 33 into an outer slot. The stator segment may be easily removed from the support structure by sliding the core segment linking portion 33 out of the outer slot.

The inner radial periphery of sleeve 145 similarly is constructed with ribs to form grooves and inner slots. The inner slots, which accommodate power modules 47, are radially aligned with the outer slots. At a relatively central portion of each paired slot is a cutout 150 in sleeve 145. The power modules contain the control and switch circuitry for controlled energization of stator winding 34 formed on the stator segment in the opposite slot. The cutout permits electrical connection between the power module and the stator winding. As can be seen in Fig. 7c, the power module package conforms to

the dimension of the inner slot and can readily be inserted or removed therefrom.

It is to be understood that the number of stator segments shown has been chosen merely for illustration, as any particular number of stator poles may be provided, depending upon desired operating criteria. The distance between spines 142 in the illustrated embodiment spaces three sets of stator core segments and provides space for placement of energy sources and one or a plurality of controllers. The number of spines, of course, can be varied in light of structural considerations.

In this disclosure there is shown and described only preferred embodiments of the invention and but a few examples of its versatility. It is to be understood that the invention is capable of use in various other combinations and environments and is capable of changes or modifications within the scope of the inventive concept as expressed herein. For example, as can be appreciated, the motor of the invention can be utilized in a wide range of applications in addition to vehicle drives. Additionally, while it is preferable to provide a separate energy supply for each module for reasons described above, a single source of sufficient capacity may be used to supply a plurality of stator segment windings.

It is within contemplation that the embodiment of Figs. 7a - 7c is applicable to circumferential alignment of core segment pole pairs, as well as the axial aligned arrangement illustrated. Thus, for example, the stator core sections shown in Figs. 1 and 6 may comprise linking portions that conform in shape to

outer slots of a stator supporting structure, such as shown in Figs. 7a - 7c. Inner slots may be provided for containment of electrical components.